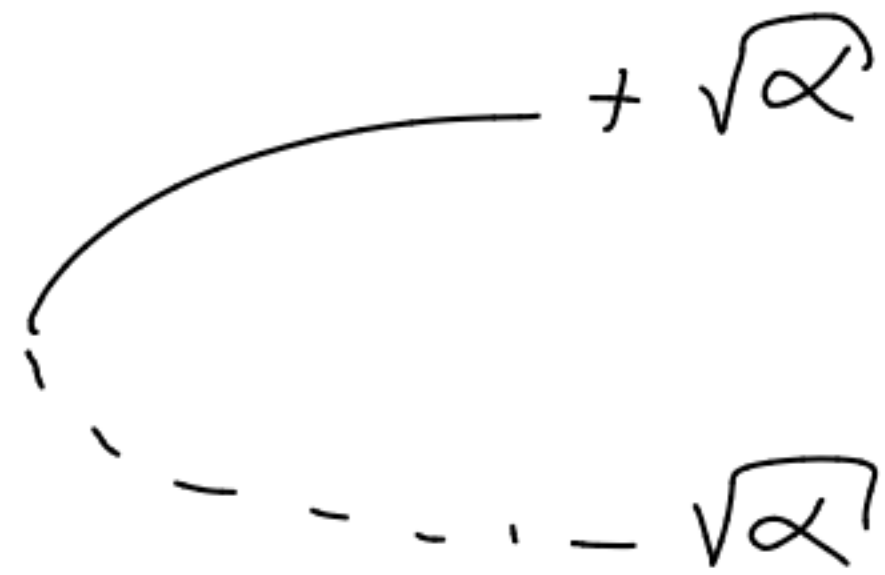
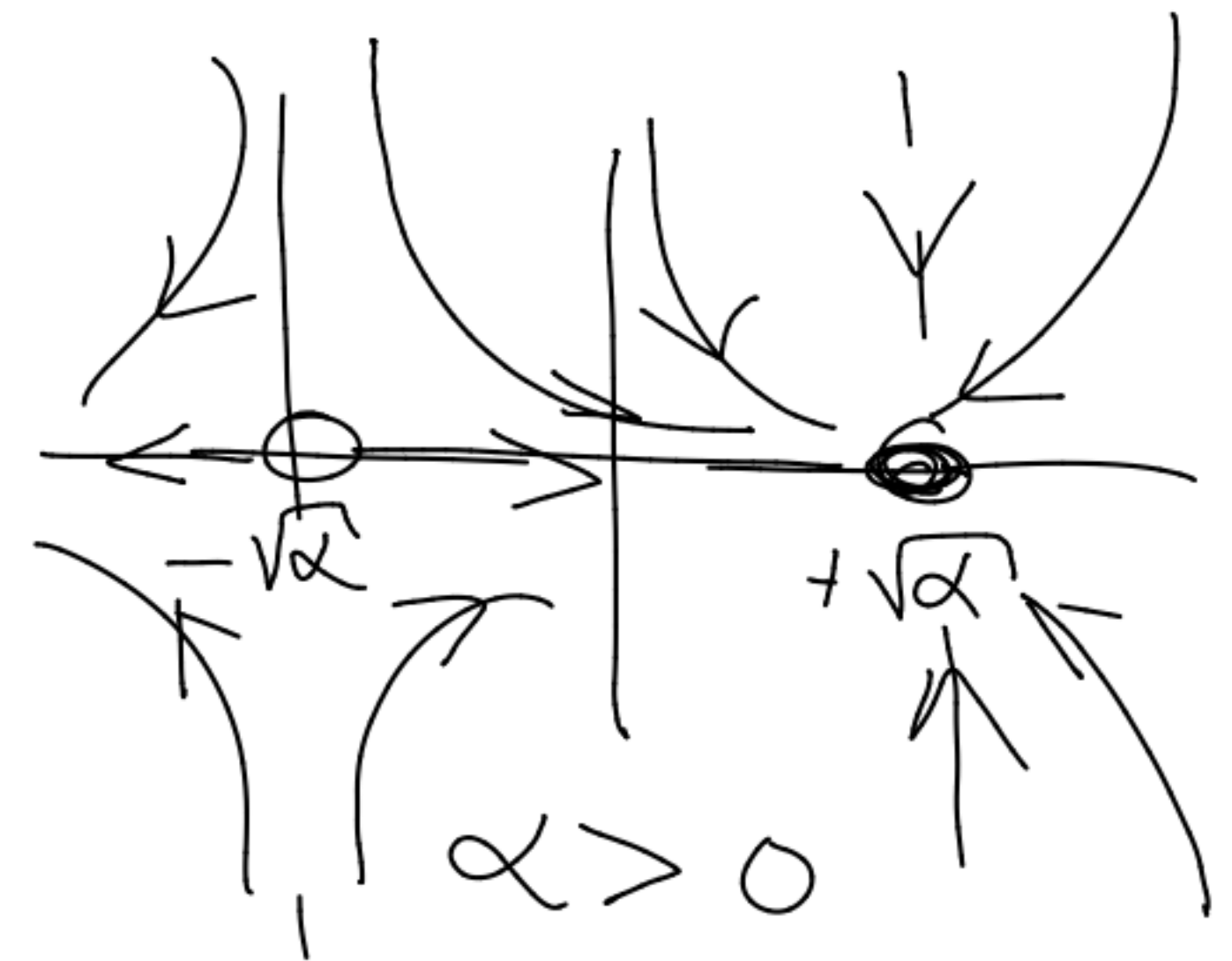
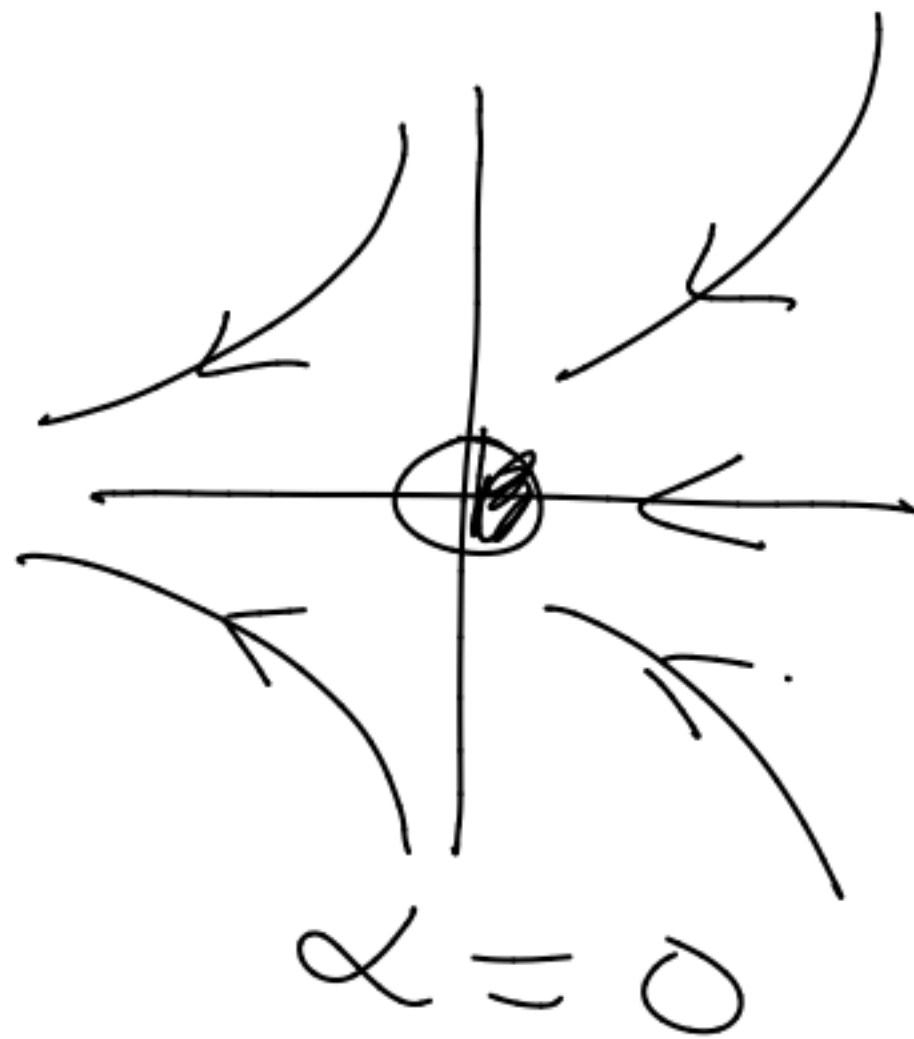
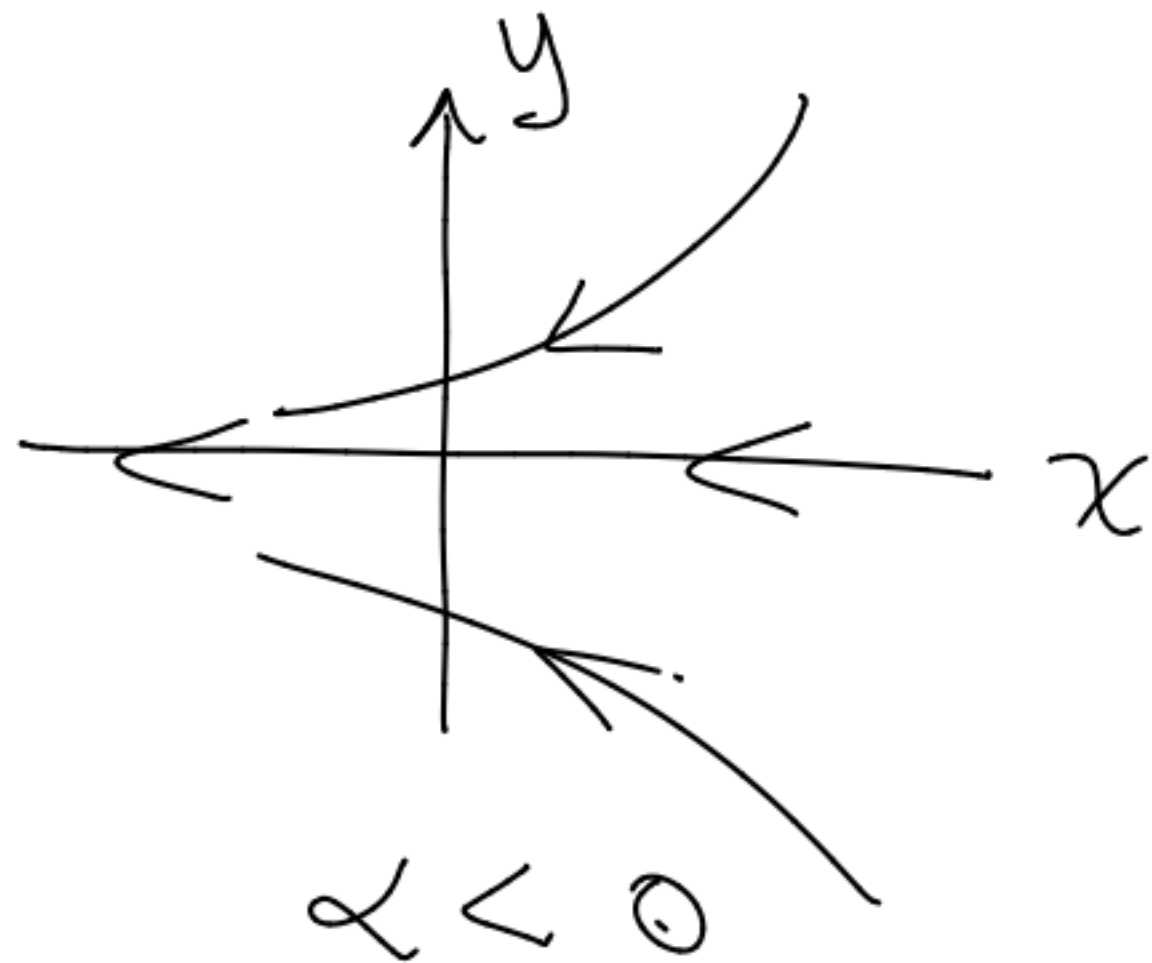
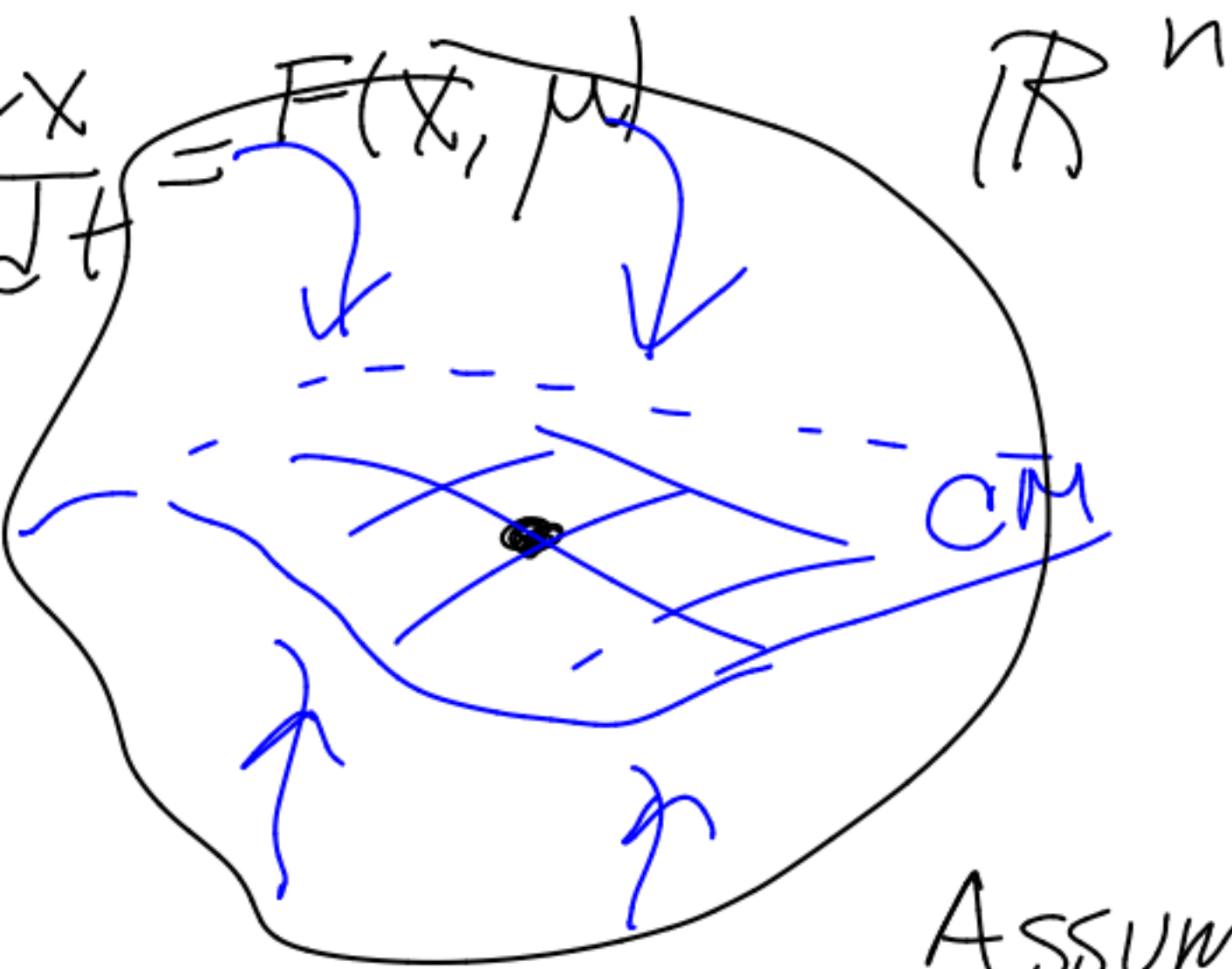


Center Manifold

e.g.) $\dot{x} = \alpha - x^2$
 $\dot{y} = -y$





Let

$$\dot{x} = Ay + f(x, y)$$

$$\dot{y} = By + g(x, y), \quad (x, y) \in \mathbb{R}^c \times \mathbb{R}^s$$

Assume: $f(0, 0) = g(0, 0) = 0$

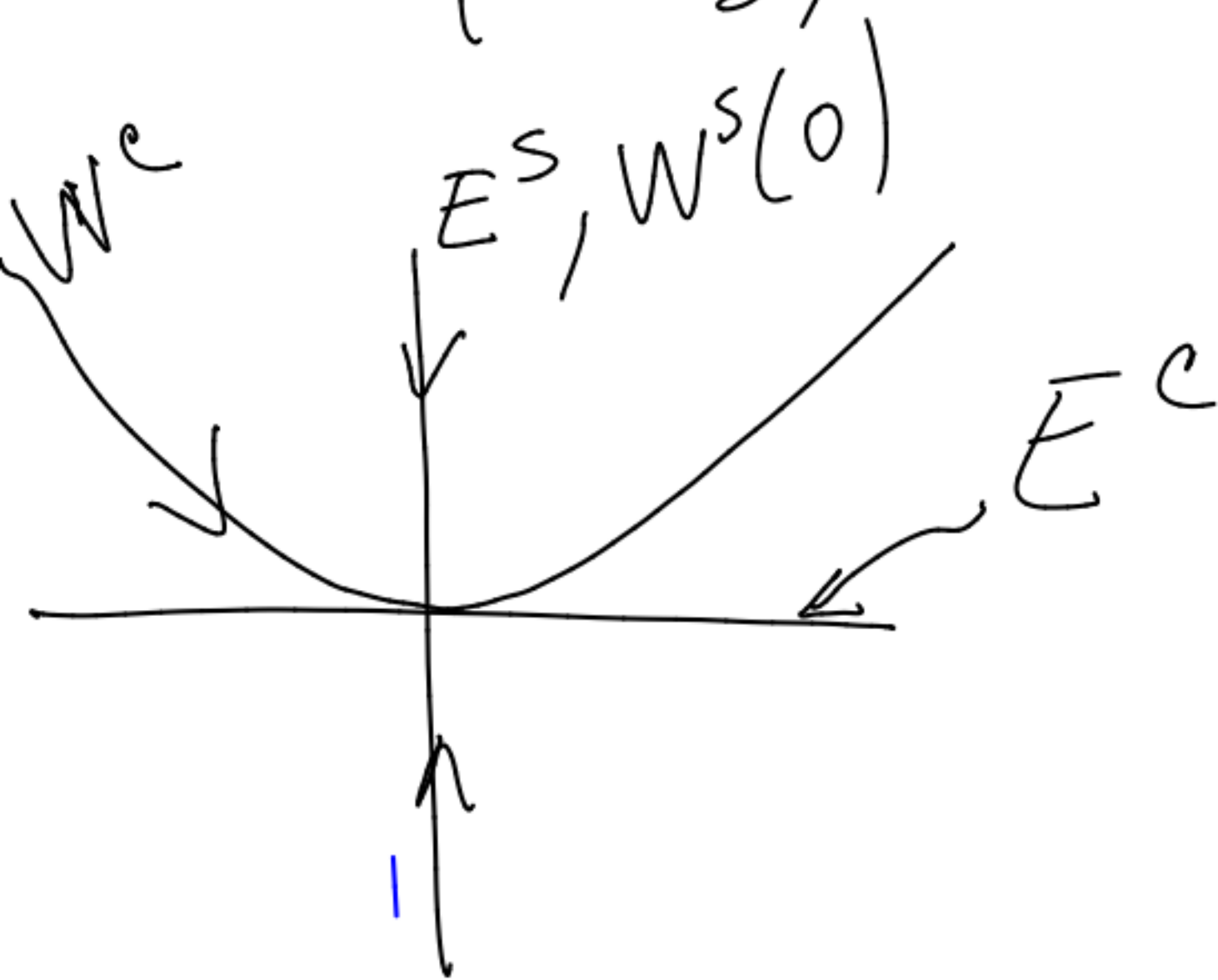
$$Df(0, 0) = Dg(0, 0) = 0$$

$A_{c \times c}$ — e-evals with zero real part

$B_{s \times s}$ — „ negative „

Def An invariant manifold is a Center Manifold for (1) if it can be locally represented as

$$W^c = \left\{ (x, y) \in \mathbb{R}^c \times \mathbb{R}^s : y = h(x), |x| < \delta, \underbrace{h(0)=0, Dh(0)=0}_{W^c \text{ is tangent to } E^c} \right\}$$



Thm There exists a C^r C.M. for (1) where the dynamics of (1), restricted to CM, is

$$\dot{u} = Au + f(u, h(u)) \quad (2)$$

Theorem

(i) Suppose Equil. of (2) is stable (unstable)

Then the " (1) "

(i) Suppose Equil. of (2) is stable

Then if $(x(t), y(t))$ is a sol. of (1) with $(x(0), y(0))$ small, then there is a sol.

$u(t)$ of (2) st. as $t \rightarrow \infty$:

$$x(t) = u(t) + O(e^{-\gamma t}) \quad \lim_{t \rightarrow \infty} y(t) = h(x)$$
$$y(t) = h(u(t)) + O(e^{-\gamma t})$$

where γ is a constant

/

Algorithm

S1 We seek: $y=h(x)$

S2 Diff. w.r.t. t : $\dot{y} = Dh(x) \dot{x}$ (3)

S3 Substitute $y=h(x)$ in (1)

$$\dot{x} = Ax + f(x, h(x))$$

$$\dot{y} = Bh(x) + g(x, h(x))$$

Substituting into (3):

$$Dh(x) [Ax + f(x, h(x))] = Bh(x) + g(x, h(x))$$

$$V(h(x)) = Dh(x) [Ax + f(x, h)] - Bh - g(x, h) = 0$$

$$\begin{aligned} \text{2.9.) } \dot{x} &= x^2 y - x^5 \\ \dot{y} &= -y + x^2 \end{aligned}$$

$$\underline{s1} \quad E_1(0,0)$$

$$\underline{s2} \quad J = \begin{bmatrix} 2xy - 5x^4 & x^2 \\ 2x & -1 \end{bmatrix}$$

$$J|_{E_1} = \begin{bmatrix} 0 & 0 \\ 0 & -1 \end{bmatrix}$$

$$\begin{aligned} \underline{s3} \quad \dot{x} &= 0x + (x^2 y - x^5) \\ \dot{y} &= -1y + (x^2) \end{aligned}$$

$$\text{Let } y = h(x) = ax^2 + bx^3 + \dots$$

$$N(W) = (2ax + 3bx^2 + \dots) \left(0 + ax^4 + bx^5 - x^5 \right) + (ax^2 + bx^3 + \dots) - x^2 \stackrel{\text{set}}{=} 0$$

Equating like powers of x :

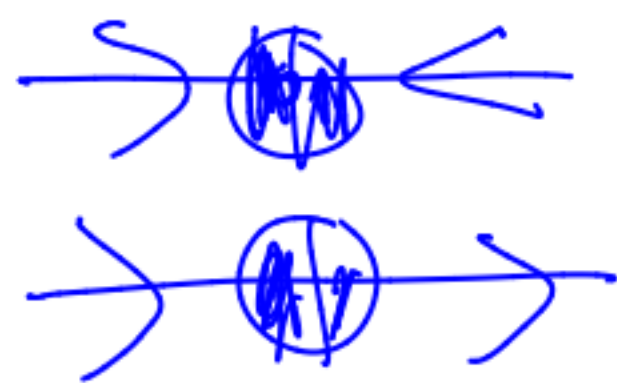
$$x^2: a - 1 = 0$$

$$x^3: b = 0$$

$$\therefore h(x) = x^2 + O(x^4)$$

$$\text{Thm} \Rightarrow \dot{u} = 0 \cdot u + u^4 + O(x^5)$$

$$\begin{aligned} \text{① } \dot{x} &\approx -x^5 \\ u &= u^4 \end{aligned}$$



e.g.) Lorenz Model

$$\begin{aligned}\dot{x} &= \sigma(y-x) \\ \dot{y} &= \bar{\rho}x + x - y - xz \\ \dot{z} &= -\beta z + xy\end{aligned}$$

sl $E, (0,0,0)$

$$\text{sl } J|_{E_1} = \begin{bmatrix} -\sigma & \sigma & 0 \\ 1 & -1 & 0 \\ 0 & 0 & -\beta \end{bmatrix}$$

e-vals: $0, -\sigma-1, -\beta$

e-vec: $\begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} \sigma \\ -1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$

Let $P = \begin{bmatrix} 1 & \sigma & 0 \\ 1 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix}, \begin{bmatrix} x \\ y \\ z \end{bmatrix} = P \begin{bmatrix} u \\ v \\ w \end{bmatrix}$

$$\Rightarrow \begin{bmatrix} \dot{u} \\ \dot{v} \\ \dot{w} \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & -(\sigma+1) & 0 \\ 0 & 0 & -\beta \end{bmatrix} \begin{bmatrix} u \\ v \\ w \end{bmatrix} +$$

$$\begin{bmatrix} \sigma \bar{\rho}(u+\sigma v) - \sigma w(u+\sigma v) \\ -\bar{\rho}(u+\sigma v) + w(u+\sigma v) \\ (1+\sigma)(u+\sigma v)(u-v) \end{bmatrix}$$

Let $\bar{\rho} = 0$

$$v = h_1(u, \bar{\rho}) = a_1 u^2 + a_2 u \bar{\rho} + a_3 \bar{\rho}^2 + \dots$$

$$w = h_2(u, \bar{\rho}) = b_1 u^2 + b_2 u \bar{\rho} + b_3 \bar{\rho}^2 + \dots$$

CM Algorithm

$$h_1(u, \bar{e}) = -\frac{1}{(1+\sigma)^2} u \bar{e} + \dots,$$

$$h_2(u, \bar{e}) = \frac{1}{\beta} u^2 + \dots,$$

$$\begin{aligned} \dot{u} &= \frac{1}{1+\sigma} u \left(\sigma \bar{e} - \frac{\sigma}{\beta} u^2 + \dots \right) \\ \dot{\bar{e}} &= 0 \end{aligned}$$

