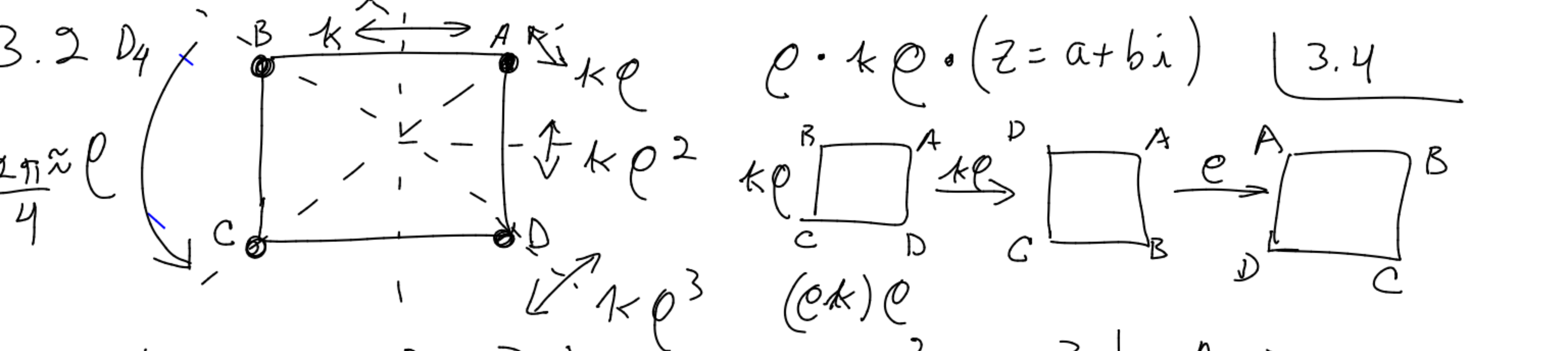




	e	ρ	ρ^2	ρ^3	k	$k\rho$	$k\rho^2$	$k\rho^3$
e	e	ρ	ρ^2	ρ^3	k	$k\rho$	$k\rho^2$	$k\rho^3$
ρ	ρ	ρ^2	ρ^3	e	k	$k\rho$	$k\rho^2$	$k\rho^3$
ρ^2	ρ^2	ρ^3	e	ρ	k	$k\rho$	$k\rho^2$	$k\rho^3$
ρ^3	ρ^3	e	ρ	ρ^2	k	$k\rho$	$k\rho^2$	$k\rho^3$
k	k	$k\rho$	$k\rho^2$	$k\rho^3$	e	ρ	ρ^2	ρ^3
$k\rho$	$k\rho$	$k\rho^2$	$k\rho^3$	e	ρ	ρ^2	ρ^3	e
$k\rho^2$	$k\rho^2$	$k\rho^3$	e	ρ	ρ^2	ρ^3	e	ρ
$k\rho^3$	$k\rho^3$	e	ρ	ρ^2	ρ^3	e	ρ	ρ^2

Axioms

$\gamma, \gamma_2 \in \Gamma$

$(\gamma, \gamma_2) \gamma_3 = \gamma, (\gamma_2 \gamma_3)$

$\gamma e = e \gamma = \gamma$

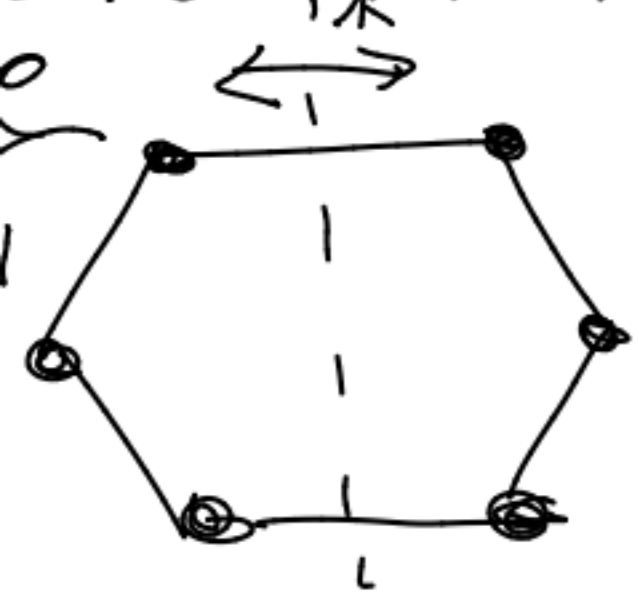
$\gamma^{-1} \gamma = \gamma \gamma^{-1} = e$

- 4 - Find subgroups of D_4
 - Find normal subgroups.

subgroups: $H = \{ \{e\}, \{e, \kappa\}, \{e, \rho, \rho^2, \rho^3\}, \dots \}$

$$N(H) = \{ H\gamma = \gamma H \}$$

3.5 Find Normalizers of $D_2, Z_2 \subset D_6$



$$N(D_2) = \{ \gamma \in D_6 : D_2 \gamma = \gamma D_2 \}$$

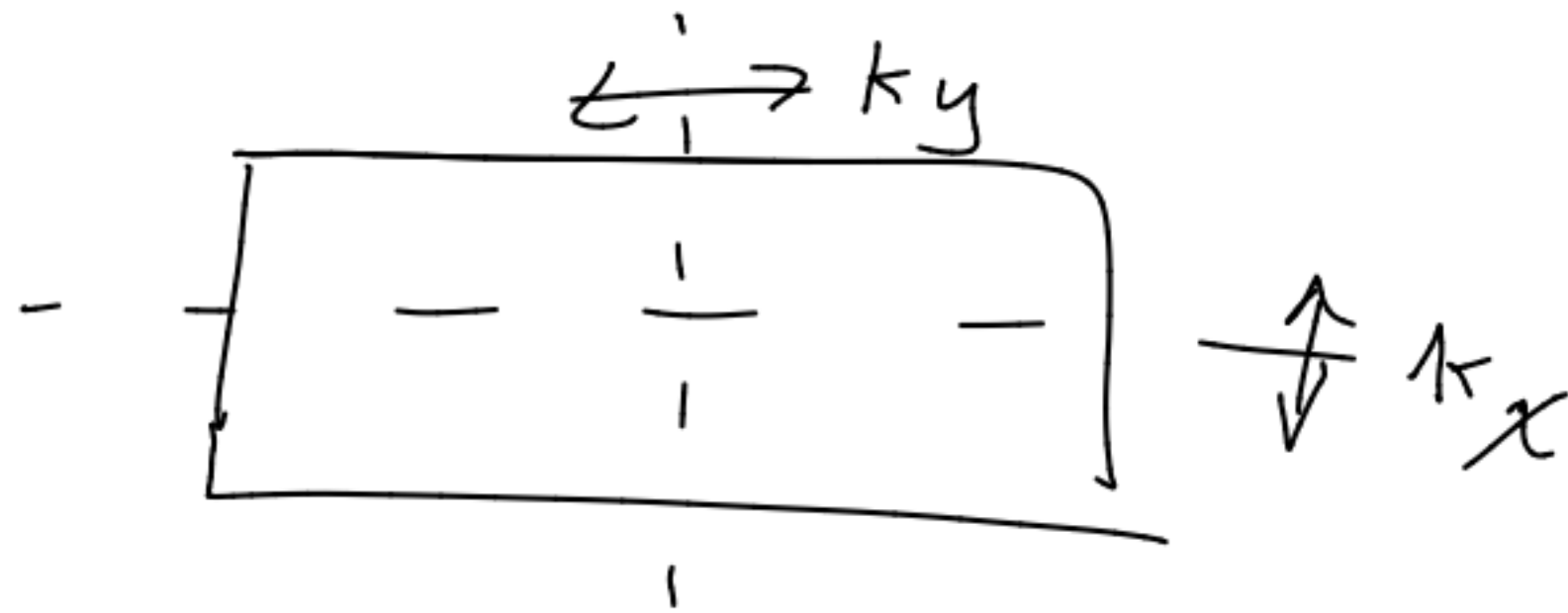
$$N(Z_2) = \{ \gamma \in D_6 : Z_2 \gamma = \gamma Z_2 \}$$

Idea: Look for the largest subgroup $K \subset \Gamma$

st. $H \subseteq K \subseteq \Gamma$ and H is normal.

$$N(Z_2) = \{ e, \rho^3, \kappa, \kappa \rho^3 \}$$

$$D_2 = \{k_x, k_y\} = \{e, k_x, k_y, k_x k_y\}$$



$$k_x \cdot r = r \cdot k_x$$

3.6 Find conjugacy classes of D_6

Suggestion: Consider the natural rep.

$$D_6 = \{e, \rho, \rho^2, \rho^3, \rho^4, \rho^5, \kappa, \kappa\rho, \kappa\rho^2, \kappa\rho^3, \kappa\rho^4, \kappa\rho^5\}$$



$$M = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \quad M_{\rho^2} \quad M_{\rho^3} \dots$$

$$R_{\frac{2\pi}{6}} = \begin{bmatrix} \cos \frac{2\pi}{6} & -\sin \frac{2\pi}{6} \\ \sin \frac{2\pi}{6} & \cos \frac{2\pi}{6} \end{bmatrix}$$

$$\chi(M_e) = 2, \chi(M_{\rho}), \dots$$

Conjugacy classes:

$$\{e\}, \{\rho, \rho^5\}, \{\rho^2, \rho^4\}, \dots$$

3.7 find irreps. of D_2 over $\mathbb{C}$

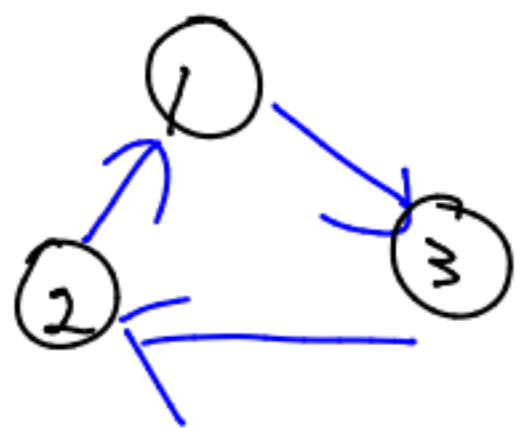
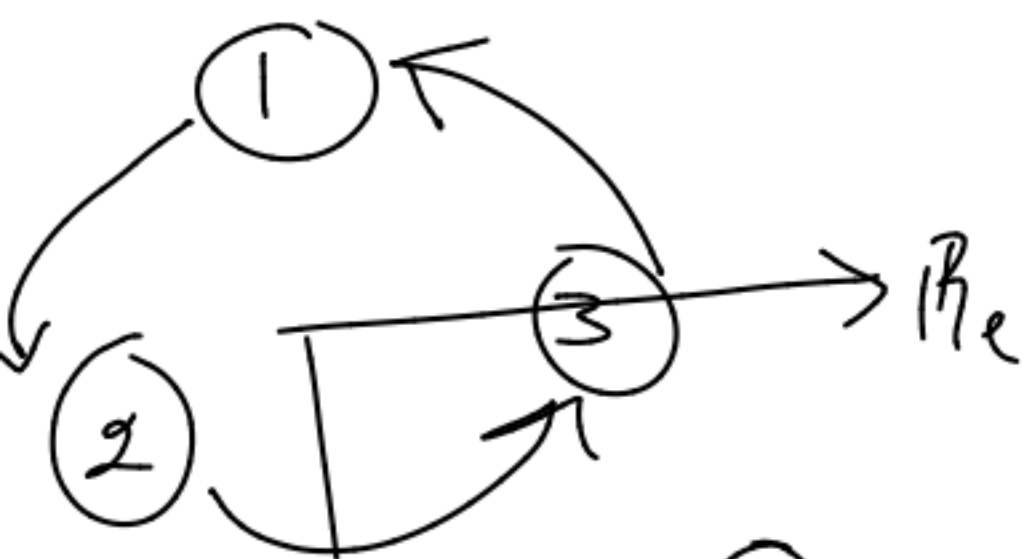
	e	k_x	k_y	$k_x k_y$
e	e	k_x	k_y	$k_x k_y$
k_x	k_x	e	$k_x k_y$	k_y
k_y	k_y	$k_x k_y$	e	k_x
$k_x k_y$	$k_x k_y$	k_y	k_x	e

	$\{e\}$	$\{k_x\}$	$\{k_y\}$	$\{k_x k_y\}$
Θ_1	1	1	1	1
Θ_2	1	1	-1	-1
Θ_3	1	-1	1	-1
Θ_4	1	-1	-1	1

3.8 Find irrep. of $\mathcal{Z}_3$ over k

$$\mathcal{Z}_3 = \{0, 1, 2\} \text{ or } \mathcal{Z}_3 = \{e, e, e^2\}$$

$$\rho = \mathbb{R} \frac{2\pi}{3} \text{ or } \rho = e^{\frac{2\pi}{3}i}$$



	$\{e\}$	$\{e\}$	$\{e^2\}$
$\mathbb{1} \theta_1$	1	1	1
$\mathbb{1} \theta_2$	e^0	$\rho^1 e^{\frac{2\pi}{3}i}$	$\rho^2 e^{\frac{4\pi}{3}i}$
$\mathbb{1} \theta_3$	1	$\rho^2 = e^{\frac{4\pi}{3}i}$	$\rho = e^{\frac{2\pi}{3}i}$

3. 8 find isotypic decomp. of $\mathbb{Z}_2$ on $\mathbb{R}^2$

Action of $\mathbb{Z}_2$ on $\mathbb{R}^2$ is

$$M_e = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \text{ and } M_k = \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix}$$

Want: $\mathbb{R}^2 = V_1 \oplus V_2$, st. $\gamma V_i \in V_i, \forall \gamma \in \Gamma = \mathbb{Z}_2$

Idea: All vectors in $\mathbb{R}^2$ can be expressed as the sum of two vectors: v_1, v_2 : $v = c_1 v_1 + c_2 v_2$

$$\text{Let } B_1 = \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\} \text{ or } \left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ -1 \end{bmatrix} \right\} = B_2$$

$$\begin{aligned} M_e v_1 &= \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \in V_1 \\ M_e v_2 &= \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix} \in V_2 \end{aligned} \quad \left[\begin{bmatrix} 1 \\ 0 \end{bmatrix} \text{ is inv. under } e \in \mathbb{Z}_2 \right]$$

and $\begin{bmatrix} 0 \\ 1 \end{bmatrix}$ is also inv. under e

$$M_K \cdot v_1 = \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} -1 \\ 0 \end{bmatrix} = (-1) \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

Show v_1 & v_2
are both $\mathbb{Z}_2$ -inv.

$$M_K \cdot v_2 = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ -1 \end{bmatrix} = (-1) \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

Let $T = S_n$

$$\mathbb{R}^n = \left[\begin{array}{c} 1 \\ \vdots \\ 1 \end{array} \right]_{ID} \oplus \left\{ \begin{array}{l} v_1 + v_2 + \dots + v_n = 0 \\ (n-1) \text{ ID} \end{array} \right\}$$

