

Reaction-Diffusion Systems

Let $c(x, t) \equiv$ Concentration of a species
(cells, chemicals, heat)

$J(x, t) \equiv$ Flux $\equiv$ amount of material being
transported

Fickian diffusion: $J \propto - \frac{dc}{dx}$
diffusion transports matters
from high-to-low concentration

$$J = -D \frac{\partial c}{\partial x}$$

diffusion coefficient

e.g.) Blood molecules: $D = 10^{-7} \frac{\text{cm}^2}{\text{sec}}$

oxygen in blood: $D = 10^{-5} \frac{\text{cm}^2}{\text{sec}}$

Conservation Equation

$$\left[\begin{array}{l} \text{Rate of change} \\ \text{of some material} \\ \text{in a region} \end{array} \right] = \left[\begin{array}{l} \text{rate of flow} \\ \text{across} \\ \text{boundary} \end{array} \right] + \left[\begin{array}{l} \text{material created} \\ \text{inside} \end{array} \right]$$

$$\underbrace{\frac{2}{2t} \int_{x_0}^{x_1} c(x,t) dx}_{\text{Total amount of material}} = \underbrace{J(x_0,t) - J(x_1,t)}_{\text{rate of flow across } x_0 < x < x_1}$$

rate of change

$$\int_{x_0}^{x_1} \frac{\partial c(x,t)}{\partial t} dx$$

$$= - \int_{x_0}^{x_1} \frac{\partial J}{\partial x} dx$$

$$\boxed{\int_{x_0}^{x_1} \left(\frac{\partial c}{\partial t} + \frac{\partial J}{\partial x} \right) dx = 0}$$

Integral
Conservation
Law

$\int (\cdot) dx = 0$ for arbitrary regions

$$\Rightarrow (\cdot) = 0$$

Diffusion Eq.

Since $J = -D \frac{\partial c}{\partial x} \Rightarrow$

$$\frac{\partial c}{\partial t} = \frac{\partial}{\partial x} \left(D \frac{\partial c}{\partial x} \right)$$

If $D = \text{constant} \Rightarrow$

$$\frac{\partial c}{\partial t} = D \frac{\partial^2 c}{\partial x^2}$$

Let $V = 3D$ space

$S \equiv$ Arbitrary surface enclosing V

$$\frac{2}{2t} \int_V c(\vec{x}, t) dV = - \int_S \vec{J} \cdot d\vec{S} + \int_V \underset{\substack{\uparrow \\ f(c, \vec{x}, t)}}{f} dV$$

Assume c to be continuous

Recall: $\int_V \nabla \cdot \vec{J} dV = \int_S \vec{J} \cdot d\vec{S}$

$$\int_V \left[\frac{2c}{2t} + \nabla \cdot \vec{J} - f(c, \vec{x}, t) \right] dV = 0$$

$$\Rightarrow \boxed{\frac{2c}{2t} + \underbrace{\nabla \cdot \vec{J}}_{\text{scalar}} = f(c, \vec{x}, t)} \quad \begin{array}{l} \text{Conservation} \\ \text{Eq. for } c \end{array}$$

$$\frac{\partial c}{\partial t} = f + \underbrace{\nabla \cdot (D \underbrace{\nabla c}_{\text{gradient}})}_{\text{scalar}}$$

$$D = D(x, c), \text{ i.e. biomedical appl.}$$

$$D = \text{constant} \Rightarrow \left| \frac{\partial c}{\partial t} = f + \underbrace{D \nabla^2 c}_{\text{reaction diffusion}} \right|$$

Generalization

$$\vec{u} = \begin{bmatrix} u_1(\vec{x}, t) \\ u_2(\vec{x}, t) \\ \vdots \\ u_m(\vec{x}, t) \end{bmatrix}, D = \begin{bmatrix} D_{11} & \dots & D_{1m} \\ \underbrace{\hspace{1cm}}_{\text{cross diffusivity}} \\ D_{m1} & \dots & D_{mm} \end{bmatrix}$$

Without cross diffusivity:

$$D = \begin{bmatrix} D_1 & & \\ & D_2 & \\ & & \ddots \end{bmatrix}$$

$$\frac{2\vec{u}}{2l} \pm f + \nabla \cdot \underbrace{(\underbrace{D \nabla \vec{u}}_{\text{tensor}})}_{\text{vector}}$$

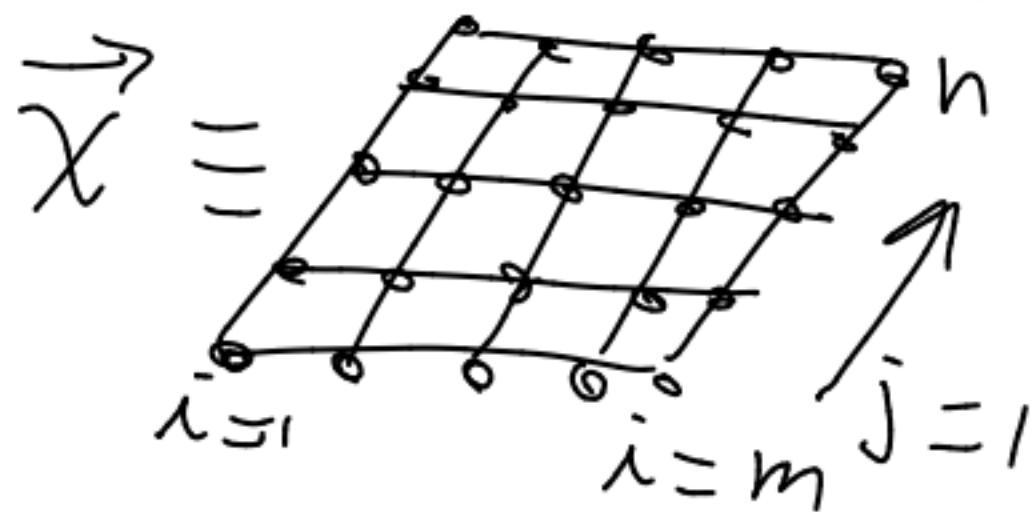
Turing Patterns (1952)

$$\frac{\partial u}{\partial t} = f(u, v) + D_u \nabla^2 u$$

$$\frac{\partial v}{\partial t} = g(u, v) + D_v \nabla^2 v$$

Let $\vec{x} \in \mathbb{R}^2, \mathbb{R}^3$

$u(\vec{x}, t), v(\vec{x}, t)$



$$\vec{x} = \begin{bmatrix} x_{11} \\ \vdots \\ x_{1m} \\ x_{21} \\ \vdots \\ x_{2m} \\ \vdots \\ x_{mn} \end{bmatrix}$$

stability
"diffusion driven
instability"

e.g.) $\vec{x} \equiv$ field of dry grass

$g \equiv$ grass hoppers
(moisture $\equiv$ inhibits)

$f \equiv$ flame front (activates)

$Q=0$: no moisture

$\Rightarrow$ fire spreads uniformly

$\Rightarrow$ steady-state $\equiv$ uniform & charred area

$Q > 0$ and $D_g > D_f$

$\Rightarrow$ moisture moves quickly ahead of flame front

$\Rightarrow$ charred area is restricted to

a finite domain

$\Rightarrow$ Pattern Formation

Conditions for Instability

Assume: $(u, v) = (u_0, v_0) \equiv$ Steady-State or Equilibrium
Spatially homogeneous sol.

$$\left. \frac{\partial u}{\partial t} \right|_{(u_0, v_0)} = 0 \Rightarrow f(u_0, v_0) + D_u \nabla^2 u_0 = 0$$

$$\left. \frac{\partial v}{\partial t} \right|_{(u_0, v_0)} = 0 \Rightarrow g(u_0, v_0) + D_v \nabla^2 v_0 = 0$$

Perturbation

$$(u_0, v_0) \equiv \text{Equil.} \Rightarrow$$

$$\begin{aligned} u &= u_0 + \tilde{u} \\ v &= v_0 + \tilde{v} \end{aligned} \quad \text{perturbation} \quad \|\tilde{u}\|, \|\tilde{v}\| \ll 1$$

Linearization

$$\frac{\partial u}{\partial t} = f(u, v) + D_u \nabla^2 u \equiv F(u, v)$$

$$\frac{\partial v}{\partial t} = g(u, v) + D_v \nabla^2 v \equiv G(u, v)$$

Linearization

$$\frac{\partial \tilde{u}}{\partial t} = \left. \frac{\partial f}{\partial u} \right|_{(u_0, v_0)} \tilde{u} + \left. \frac{\partial f}{\partial v} \right|_{(u_0, v_0)} \tilde{v} + D_u \nabla^2 \tilde{u}$$

$$\frac{\partial \tilde{v}}{\partial t} = \left. \frac{\partial g}{\partial u} \right|_{(u_0, v_0)} \tilde{u} + \left. \frac{\partial g}{\partial v} \right|_{(u_0, v_0)} \tilde{v} + D_v \nabla^2 \tilde{v}$$

$$\frac{\partial \tilde{u}}{\partial t} = a \tilde{u} - b \tilde{v} + D_u \nabla^2 \tilde{u}$$

$$\frac{\partial \tilde{v}}{\partial t} = c \tilde{u} - d \tilde{v} + D_v \nabla^2 \tilde{v}$$

Lineariz. d. System

$a, b, c, d > 0 \Rightarrow$ u - activator
 v - inhibitor

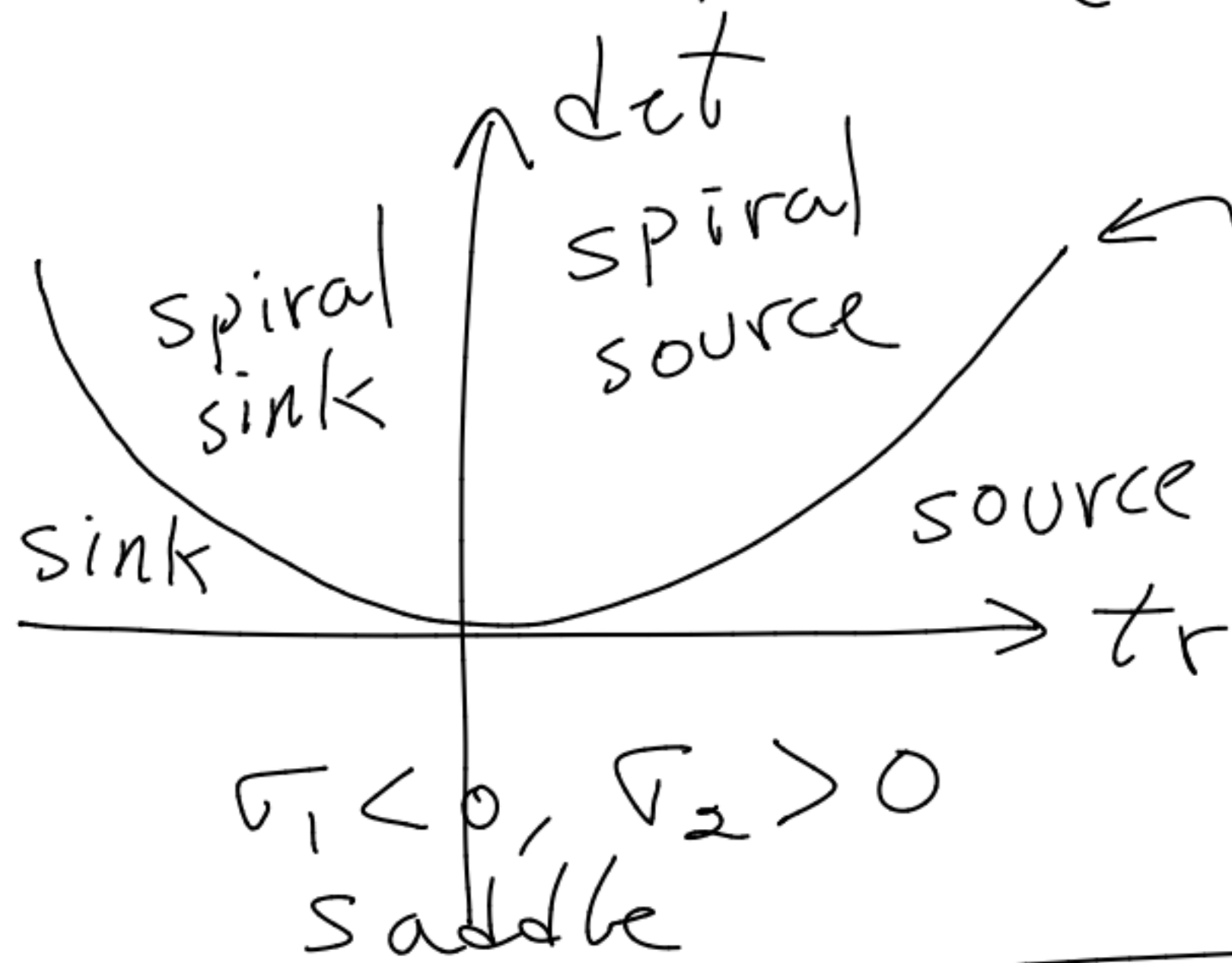
Special Case: $D_u = D_v = 0$

$$\begin{bmatrix} \frac{2\tilde{u}}{2t} \\ \frac{2\tilde{v}}{2t} \end{bmatrix} = \begin{bmatrix} a & -b \\ c & -d \end{bmatrix} \begin{bmatrix} \tilde{u} \\ \tilde{v} \end{bmatrix} = J \begin{bmatrix} \tilde{u} \\ \tilde{v} \end{bmatrix}$$

Set: $\begin{cases} \tilde{u} = \hat{u} e^{\sigma t} \\ \tilde{v} = \hat{v} e^{\sigma t} \end{cases} \left. \begin{array}{l} \sigma < 0 \Rightarrow \tilde{u}, \tilde{v} \rightarrow 0 \Rightarrow (u_0, v_0) \text{ stable} \\ \sigma > 0 \Rightarrow \tilde{u}, \tilde{v} \rightarrow \infty \Rightarrow (u_0, v_0) \text{ unstable} \end{array} \right\}$

Char. Poly: $\boxed{\sigma^2 - \text{tr}(J)\sigma + \det J = 0}$

$$\sigma^2 - (a-d)\sigma + (-ad+bc) = 0$$



$$\underbrace{(\text{tr} J)^2}_x - 4 \underbrace{\text{det} J}_y = 0$$

$$\text{Re}\{\sigma\} < 0$$

$\Downarrow$

$$\text{tr} J < 0 \text{ \& \; } \text{det} J > 0$$

$$\boxed{a < d \text{ \& \; } ad < bc}$$

$$\sigma = -\frac{1}{2} \text{tr} J \pm \frac{1}{2} \sqrt{(\text{tr} J)^2 - 4 \text{det} J}$$

$(|\text{tr} J| - \varepsilon)$

Full System

Let

$$\tilde{u}(\vec{x}, t) = \hat{u} e^{i\vec{k} \cdot \vec{x} + \sigma t} + \text{c.c.}$$

$$\tilde{v}(\vec{x}, t) = \hat{v} e^{i\vec{k} \cdot \vec{x} + \sigma t} + \text{c.c.}$$

$\vec{k}$ = wave vector

Fourier Expansion

Fourier Modes

