

Full System

Fourier Modes

Let $\tilde{u}(x, t) = \hat{u} e^{i \vec{k} \cdot \vec{x} + \sigma t} + \text{c.c.}$
 $\tilde{v}(x, t) = \hat{v} e^{i \vec{k} \cdot \vec{x} + \sigma t} + \text{c.c.}$

complex constants

Substituting into the Linearized System:

$$\begin{aligned} \sigma \hat{u} e^{i \vec{k} \cdot \vec{x} + \sigma t} &= a \hat{u} e^{i \vec{k} \cdot \vec{x} + \sigma t} - b \hat{v} e^{i \vec{k} \cdot \vec{x} + \sigma t} + D_u \nabla^2 (\hat{u} e^{i \vec{k} \cdot \vec{x} + \sigma t}) \\ \sigma \hat{v} e^{i \vec{k} \cdot \vec{x} + \sigma t} &= c \hat{u} e^{i \vec{k} \cdot \vec{x} + \sigma t} - d \hat{v} e^{i \vec{k} \cdot \vec{x} + \sigma t} + D_v \nabla^2 (\hat{v} e^{i \vec{k} \cdot \vec{x} + \sigma t}) \end{aligned}$$

$$\begin{aligned} \sigma \hat{u} &= a \hat{u} - b \hat{v} - |\vec{k}|^2 D_u \hat{u} \\ \sigma \hat{v} &= c \hat{u} - d \hat{v} - |\vec{k}|^2 D_v \hat{v} \end{aligned}$$

$$\vec{\begin{bmatrix} \hat{u} \\ \hat{v} \end{bmatrix}} = \underbrace{\begin{bmatrix} a & -b \\ c & -d \end{bmatrix}}_J \underbrace{\begin{bmatrix} \hat{u} \\ \hat{v} \end{bmatrix}}_{\vec{w}} - \underbrace{1/k^2}_{D} \underbrace{\begin{bmatrix} D_u & 0 \\ 0 & D_v \end{bmatrix}}_D \underbrace{\begin{bmatrix} \hat{u} \\ \hat{v} \end{bmatrix}}_{\vec{w}}$$

Linear System
unknowns: $(\hat{u}, \hat{v})$

$$\underbrace{(\sigma I - J + |\vec{k}|^2 D)}_A \vec{w} = \vec{0}$$

Trivial Sol. $\vec{w} = \vec{0}$
(A is inv.)
 ∞ -many sol when A is singular

$$\Rightarrow \det(\sigma I - J + |\vec{k}|^2 D) = 0, \text{ let } k^2 = |\vec{k}|^2$$

$$A = \begin{bmatrix} \sigma & 0 \\ 0 & \sigma \end{bmatrix} - \begin{bmatrix} a & -b \\ c & -d \end{bmatrix} + \begin{bmatrix} k^2 D_u & 0 \\ 0 & k^2 D_v \end{bmatrix} = \begin{bmatrix} \sigma - a + k^2 D_u & b \\ -c & \sigma + d + k^2 D_v \end{bmatrix}$$

$$\sigma^2 + \sigma(D_u k^2 + D_v k^2 - a + d) + (D_u k^2 - a)(D_v k^2 + d) + bc = 0$$

2) Steady state (U_0, V_0) $\begin{cases} \text{stable if } \operatorname{Re}(\sigma) < 0 \\ \text{unstable if } \operatorname{Re}(\sigma) > 0 \end{cases}$

Case I: No Diffusion: $D_u = D_v = 0$

Recall: $a < d \Rightarrow -a + d \geq 0$

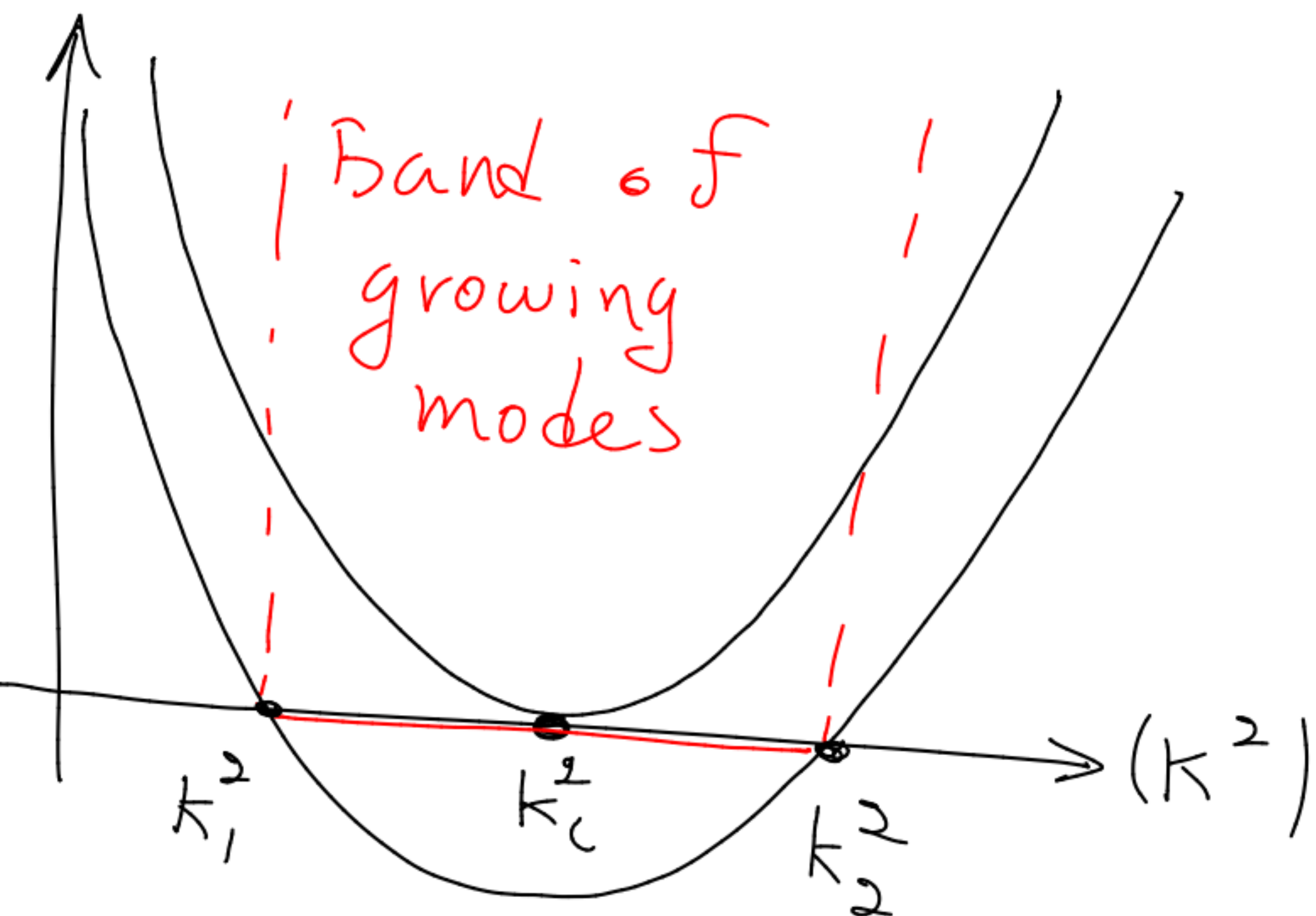
Since $(D_u + D_v)k^2 > 0$, the sum of the roots is:
 $-(D_u k^2 + D_v k^2 - a + d) < 0$

$\operatorname{Re}(\sigma) > 0$ can only happen if either

$(D_u k^2 + D_v k^2 - a + d) < 0$ (not possible)

OR $\underbrace{h(k^2)}_{\text{product of roots}} = (D_u k^2 - a)(D_v k^2 + d) + b < 0$ } quadratic in (k^2)

$$h(k^2) = D_u D_v (k^2)^2 + (d D_u - a D_v) (k^2) - ad + bc$$



$h(k^2) < 0 \Rightarrow$ inhibitor must diffuse faster for a spatial pattern to be created from the perturbation

$$h' = 2D_u D_v k^2 + (d D_u - a D_v) \stackrel{!}{=} 0$$

$$k_c^2 = \frac{1}{2} \left(\frac{a}{D_u} - \frac{d}{D_v} \right)$$

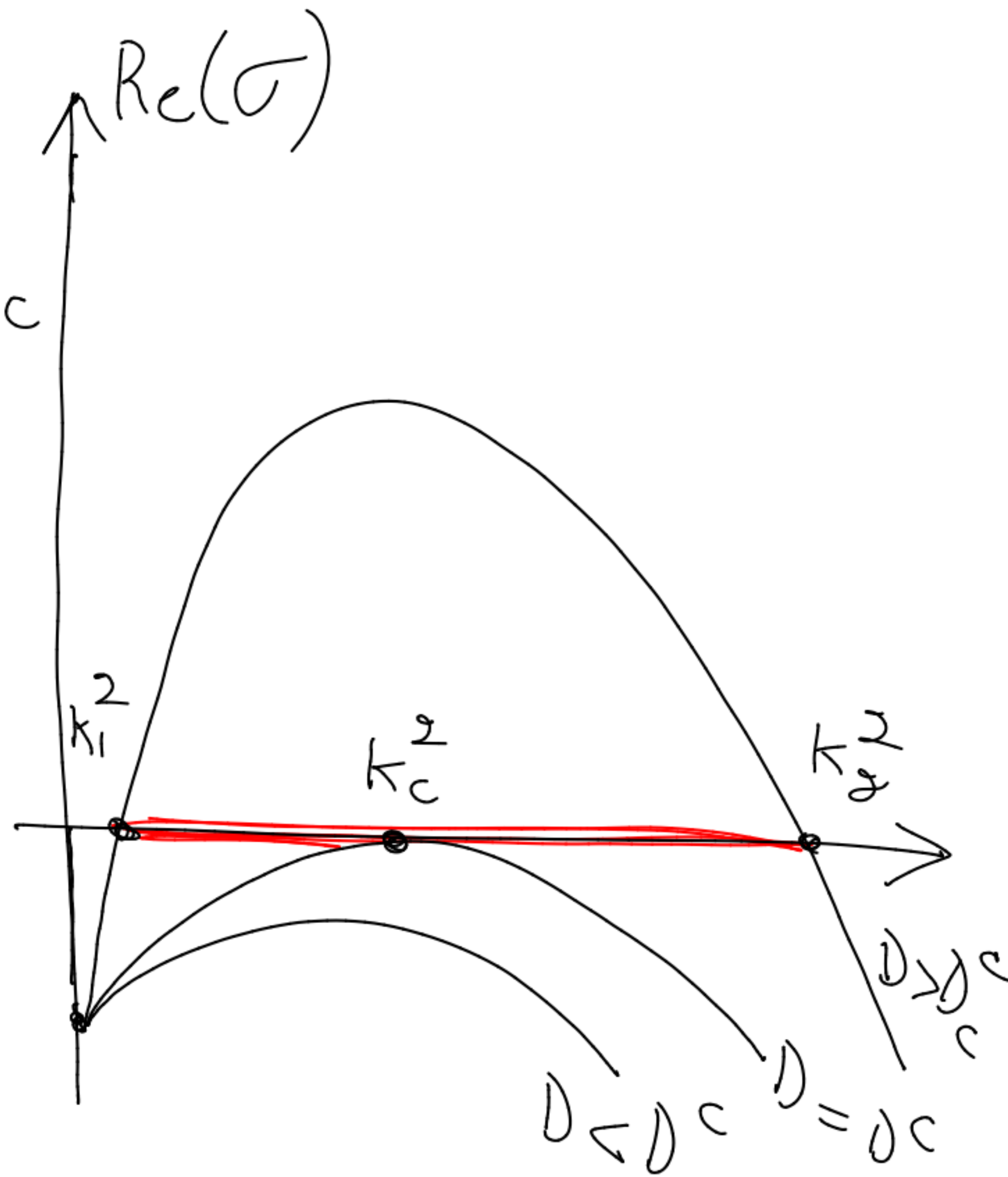
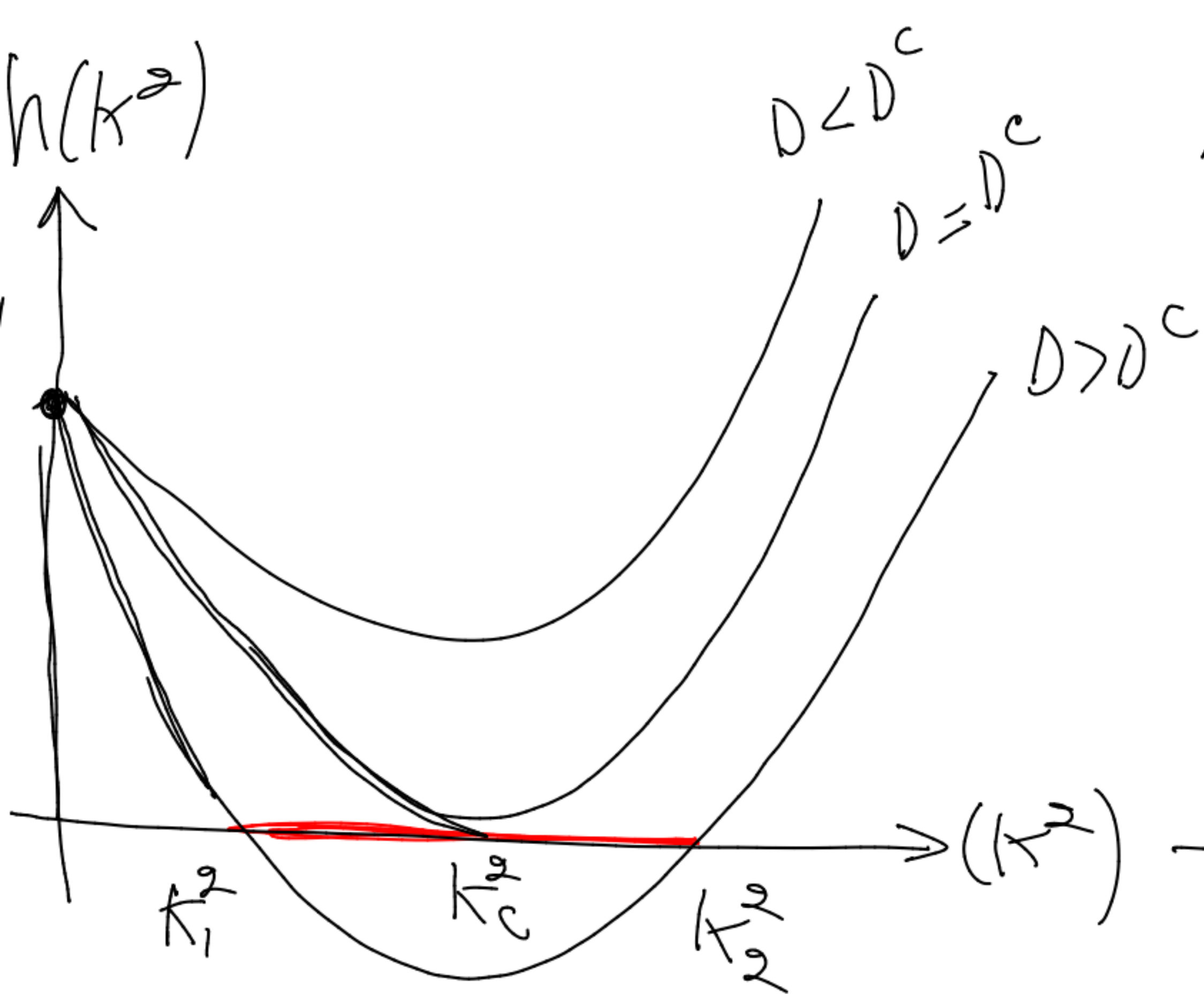
$$\min = h(k_c^2) = \dots = \left[-\frac{1}{4D_u D_v} (d D_u - a D_v)^2 - \underbrace{ad + bc}_{|J|} \right] = |J| - \frac{1}{4D_u D_v} (d D_u - a D_v)^2$$

At bif. point, $h_{\min} = 0 \iff |J| = \frac{1}{4D_u^c D_v^c} (aD_v^c - dD_u^c)^2$

$$K_c^2 = \frac{1}{2} \left(\frac{aD_v^c - dD_u^c}{D_u^c D_v^c} \right) = \frac{2\sqrt{D_u^c D_v^c} \sqrt{|J|}}{2D_u^c D_v^c} = \sqrt{\frac{|J|}{D_u^c D_v^c}} = \sqrt{\frac{bc - ad}{D_u^c D_v^c}}$$

Since $K^2 > 0$, then Turing instability occurs as long as $\frac{a}{D_u} > \frac{d}{D_v}$ and $h_{\min} < 0$

Let $D^c = D_u^c D_v^c$



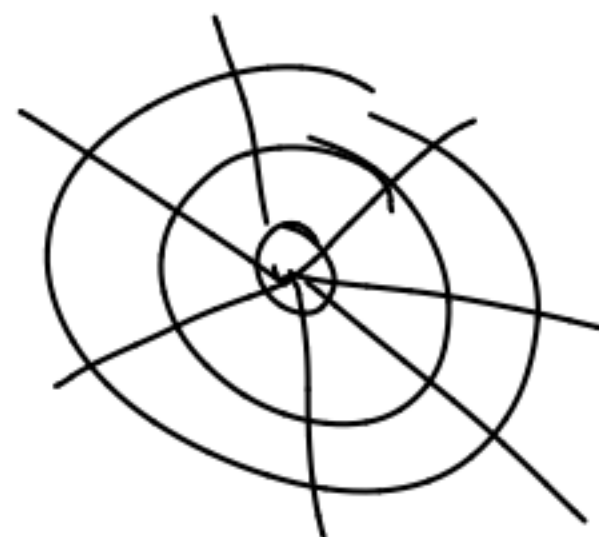
Example (Brusselator)

(Prigogine and Lefever 1974)

$$\begin{aligned}
 \frac{\partial X}{\partial t} &= \underbrace{-X^2 Y - (1 + \beta) Y}_{f(x, y)} + \alpha \underbrace{D \frac{\partial^2 X}{\partial \xi^2}}_{\text{Diffusion}} \\
 \frac{\partial Y}{\partial t} &= \underbrace{-X^2 Y + \beta X}_{g(x, y)} + D \underbrace{\frac{\partial^2 Y}{\partial \xi^2}}_{\text{Diffusion}}
 \end{aligned}$$

X, Y, α, β are chemical concentrations

$$\begin{aligned}
 X &= X(r, \theta) \\
 Y &= Y(r, \theta)
 \end{aligned}$$



$$\xi = (r, \theta), \quad 0 \leq \xi \leq R$$

