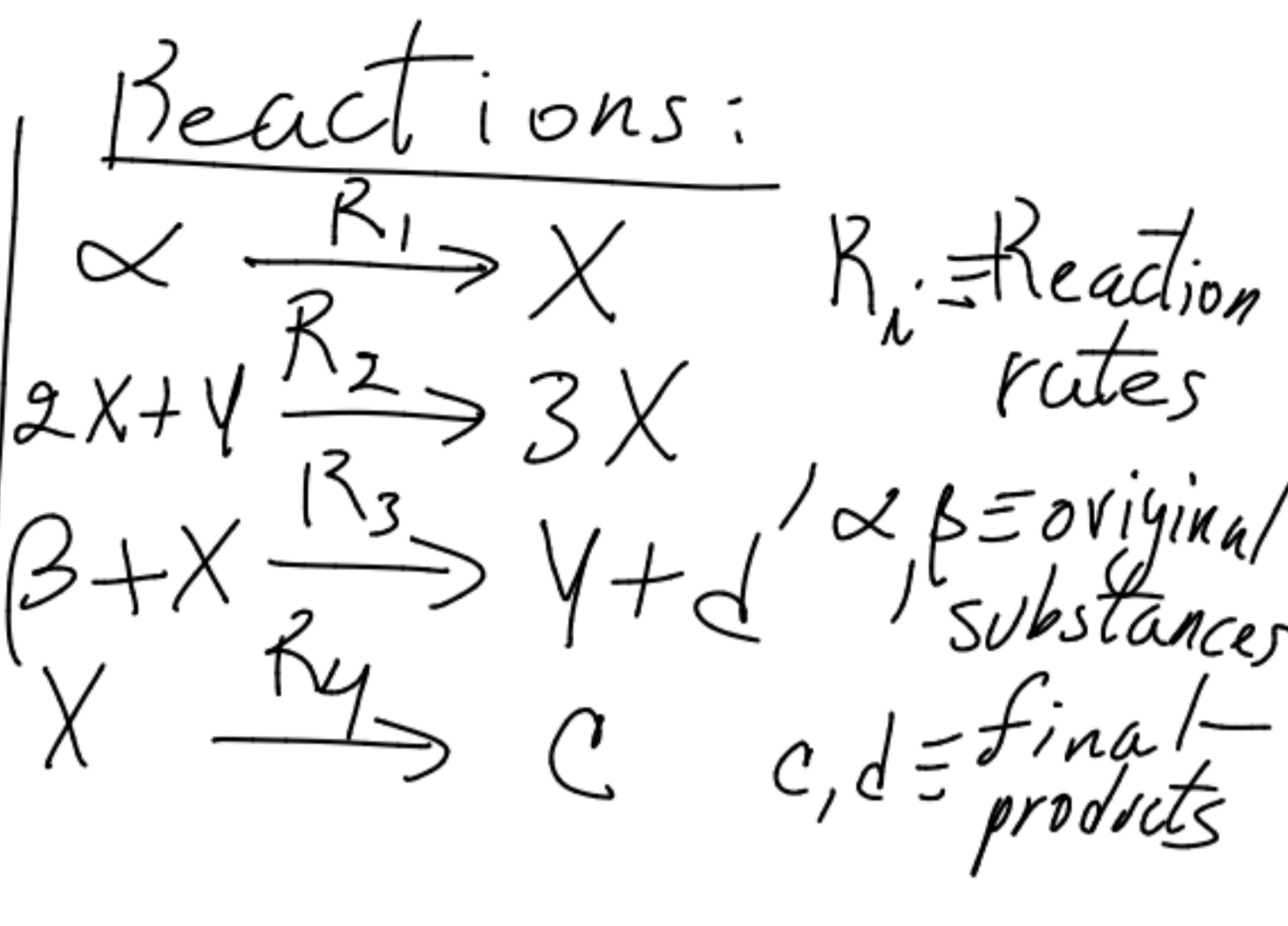


Brusselator

$$\frac{\partial X}{\partial t} = X^2 Y - (1 + \beta) X + \alpha + D_X \frac{\partial^2 X}{\partial z^2}$$

$$\frac{\partial Y}{\partial t} = -X^2 Y + \beta X + D_Y \frac{\partial^2 Y}{\partial z^2}$$



51 Equilibrium Sol

$$\begin{aligned} X^2 Y - (1 + \beta) X + \alpha + D_X \nabla^2 X &\stackrel{\text{set}}{=} 0 \\ -X^2 Y + \beta X + D_Y \nabla^2 Y &= 0 \end{aligned} \Rightarrow (\alpha, \beta/\alpha) = (X_E, Y_E)$$

Shift coord:

$$u = X - \alpha$$

$$v = Y - \beta/\alpha \Rightarrow \frac{\partial u}{\partial t} = \frac{\partial X}{\partial t}$$

$$\frac{\partial v}{\partial t} = \frac{\partial Y}{\partial t}$$

$$\frac{\partial u}{\partial t} = (u + \alpha)^2 \left(v + \frac{\beta}{\alpha} \right) - (1 + \beta)(u + \alpha) + \alpha + D_u \nabla^2 u$$

$$\frac{\partial v}{\partial t} = -(u + \alpha)^2 \left(v + \frac{\beta}{\alpha} \right) + \beta(u + \alpha) + D_v \nabla^2 v$$

$$\frac{\partial u}{\partial t} = \frac{\beta}{\alpha} u^2 + 2\alpha u v + u^2 v + (\beta - 1)u + \alpha^2 v + D_u \nabla^2 u$$

$$\frac{\partial v}{\partial t} = -\left(\frac{\beta}{\alpha} u^2 + 2\alpha u v + u^2 v \right) - \beta u - \alpha^2 v + D_v \nabla^2 v$$

$$\frac{\partial}{\partial t} \begin{bmatrix} u \\ v \end{bmatrix} = \underbrace{\begin{bmatrix} \beta - 1 & \alpha^2 \\ -\beta & -\alpha^2 \end{bmatrix} \begin{bmatrix} u \\ v \end{bmatrix} + \begin{bmatrix} D_u & 0 \\ 0 & D_v \end{bmatrix} \begin{bmatrix} \nabla^2 u \\ \nabla^2 v \end{bmatrix}}_{\text{Linear Terms}} + \underbrace{\begin{pmatrix} \frac{\beta}{\alpha} u^2 + 2\alpha u v + u^2 v \\ \alpha \end{pmatrix}}_{\text{Nonlinear}} \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

New equilibrium: $(u_0 = 0, v_0 = 0)$

Perturbation $u = 0 + \tilde{u}$
 $v = 0 + \tilde{v}$, $\begin{bmatrix} u \\ v \end{bmatrix} = \begin{bmatrix} \hat{u} \\ \hat{v} \end{bmatrix} e^{i\vec{k} \cdot \vec{x} + \sigma t} + c.c.$

Linearization about (0,0) $\nabla^2 \begin{bmatrix} \tilde{u} \\ \tilde{v} \end{bmatrix} = -k^2 \begin{bmatrix} \tilde{u} \\ \tilde{v} \end{bmatrix}$, $k^2 = |\vec{k}|^2$

$$\begin{pmatrix} \frac{\partial \tilde{u}}{\partial t} \\ \frac{\partial \tilde{v}}{\partial t} \end{pmatrix} = \underbrace{\begin{bmatrix} \beta - 1 - k^2 D_u & \alpha^2 \\ -\beta & -\alpha^2 - k^2 D_v \end{bmatrix}}_L \begin{bmatrix} \tilde{u} \\ \tilde{v} \end{bmatrix} \Rightarrow \text{e-values: } \sigma^2 - \text{tr}(J)\sigma + \det(J) = 0$$

$$\text{tr}(L) = -\alpha^2 - 1 + \beta - k^2(D_u + D_v)$$

$$\det(L) = k^2 [\alpha^2 D_u + (1 - \beta) D_v] + k^4 D_u D_v + \alpha^2 \beta = h(k^2)$$

$$= k^4 D_u D_v + k^2 [\alpha^2 D_u + (1 - \beta) D_v] + \alpha^2 (\beta) = h(k^2)$$

$$\text{tr}(L) = 0 \iff \beta = 1 + \alpha^2 + \kappa^2(D_u + D_v)$$

$$h'(\kappa^2) = 2\kappa^2 D_u D_v + \alpha^2 D_u + (1 - \beta) D_v \stackrel{\text{set}}{=} 0$$

$$\kappa^2 = \frac{1}{2 D_u D_v} \left[(\beta - 1) D_v - \alpha^2 D_u \right] \Rightarrow \boxed{\kappa_c^2 = \frac{1}{2} \left(\frac{\beta - 1}{D_u} - \frac{\alpha^2}{D_v} \right)}$$

$$h_{\min} = h(\kappa_c^2) \stackrel{\text{algebra}}{=} \dots = \alpha^2 - \frac{1}{4 D_u D_v} \left[\alpha^2 D_u - (\beta - 1) D_v \right]^2$$

$$\text{At bif. point, } h_{\min} = 0 \iff \alpha^2 = \frac{1}{4 D_u D_v} \left[\alpha^2 D_u - (\beta - 1) D_v \right]^2$$

$$\text{Solve for } \alpha^2: \alpha^2 D_u - (\beta - 1) D_v = \begin{matrix} (+) \\ (-) \end{matrix} 2\alpha \sqrt{D_u D_v}$$

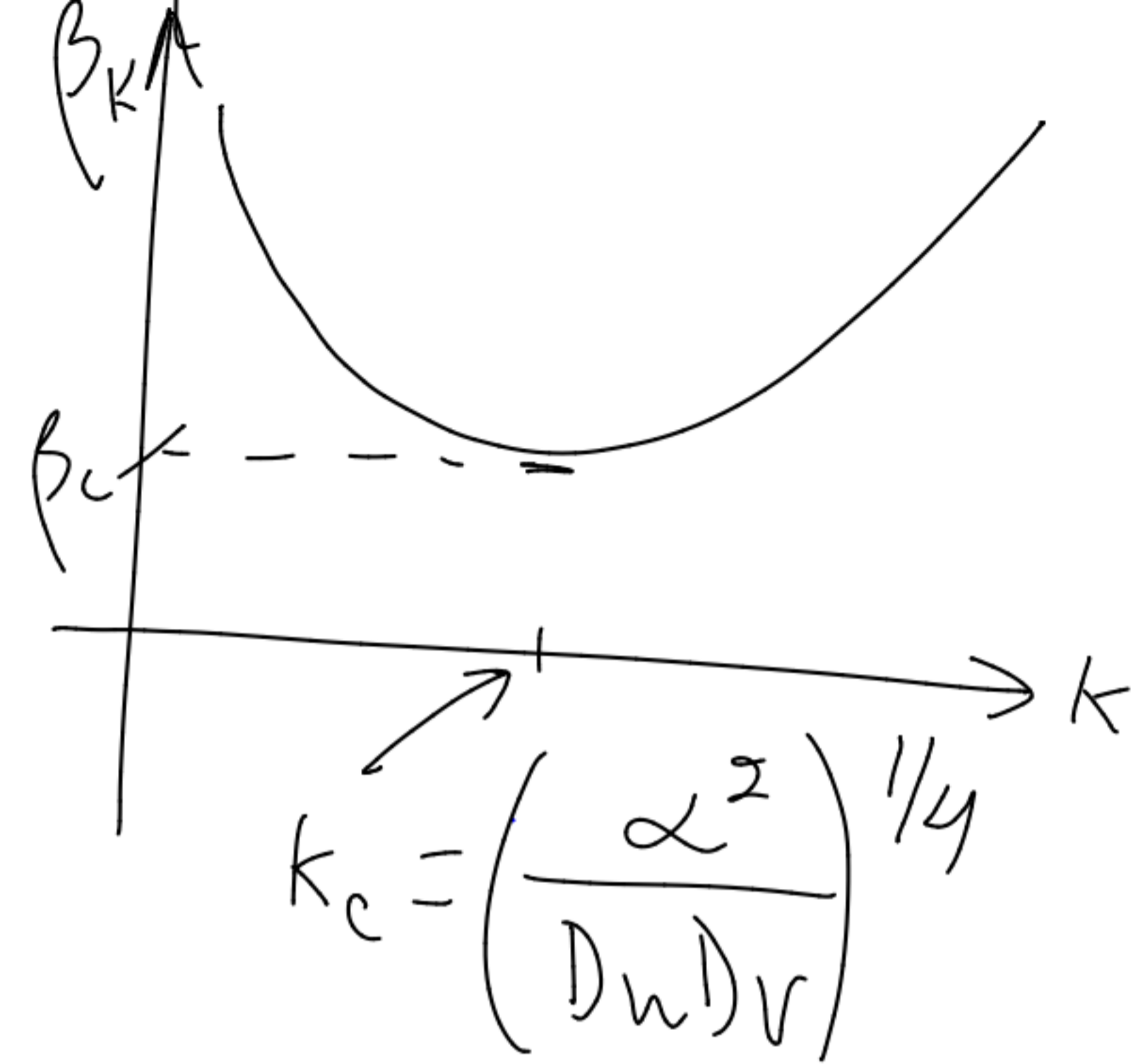
Choose "-" since $D_u \ll D_v$ and $\beta > 1$

$$(\beta-1) D_v = \alpha^2 D_u + 2\alpha \sqrt{D_u D_v}$$

$$\beta-1 = \alpha^2 \frac{D_u}{D_v} + 2\alpha \sqrt{\frac{D_u}{D_v}}$$

$$\beta_c = 1 + \alpha^2 \frac{D_u}{D_v} + 2\alpha \sqrt{\frac{D_u}{D_v}} \Rightarrow \beta_c = \left(1 + \alpha \sqrt{\frac{D_u}{D_v}}\right)^2$$

$$\begin{aligned} \Rightarrow k_c^2 &= \frac{1}{2D_u} \left[\alpha^2 \frac{D_u}{D_v} + 2\alpha \sqrt{\frac{D_u}{D_v}} \right] - \frac{1}{2D_v} (\alpha^2) \\ &= \frac{\frac{1}{2}\alpha^2 D_u + \alpha \sqrt{D_u D_v} - \frac{1}{2}\alpha^2 D_u}{D_u D_v} = \frac{\alpha}{\sqrt{D_u D_v}} \Rightarrow k_c = \left(\frac{\alpha^2}{D_u D_v}\right)^{1/4} \end{aligned}$$



$$\frac{\partial X}{\partial t} = X^2 Y - (1 + \beta)X + \alpha + D_X \nabla^2 X \quad \text{Equil.}$$

$$\frac{\partial Y}{\partial t} = -X^2 Y + \beta X + D_Y \nabla^2 Y, \quad X_E = \alpha, Y_E = \frac{\beta}{\alpha}$$

$$S1 \quad J = \begin{bmatrix} 2\bar{u}\bar{v} - (1 + \beta) & \bar{u}^2 \\ \beta - 2\bar{u}\bar{v} & -\bar{u}^2 \end{bmatrix} \Big|_{(X_E, Y_E)} = \begin{bmatrix} \beta - 1 & \alpha^2 \\ -\beta & -\alpha^2 \end{bmatrix}$$

$$|J| = \dots = \alpha^2$$

$$\Rightarrow h_{\min} = \alpha^2 - \frac{1}{4D_u D_v} [\alpha^2 D_u - (\beta - 1) D_v]^2 \stackrel{\text{set } 0}{=} 0$$

$$\Rightarrow \alpha^2 D_u - (\beta - 1) D_v = \pm 2\alpha \sqrt{D_u D_v} \Rightarrow \beta_{\min} = 1 + 2\alpha \sqrt{\frac{D_u}{D_v}} + \alpha^2 \frac{D_u}{D_v}$$

$$k_c = \left(\frac{\alpha}{D_u D_v} \right)^{1/4}$$